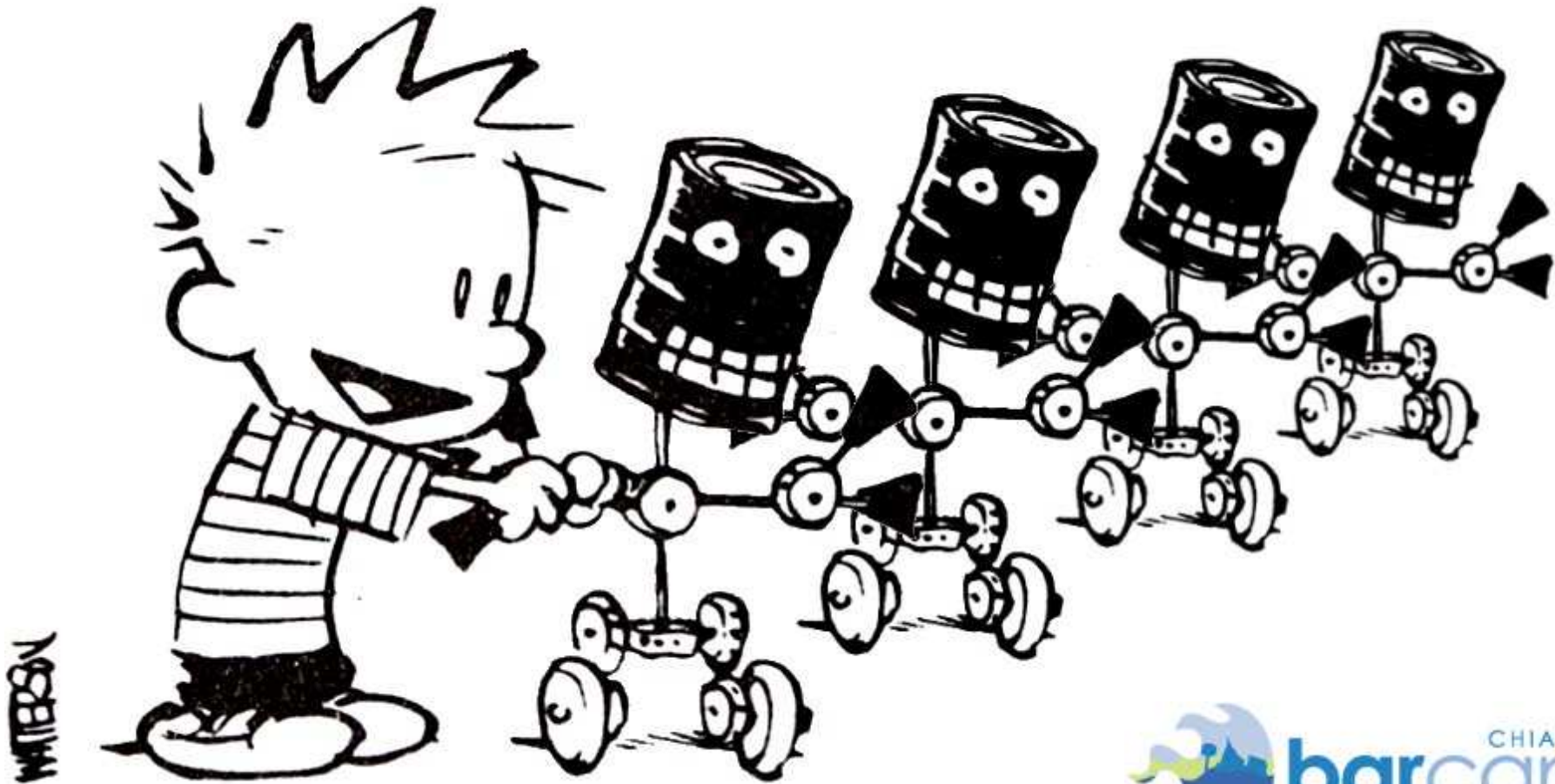


Building an Army of \$10 Robots

with  & 



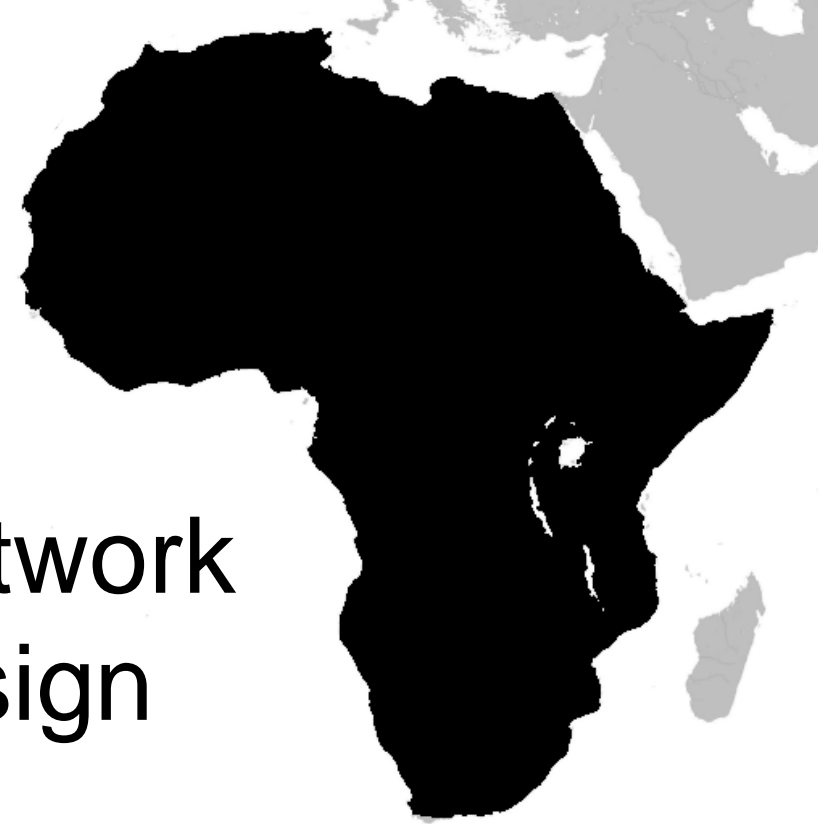
Robotics in Africa

Robots can inspire student interest in computers, science, math, & engineering but... often too expensive for African students & universities



Image: Ayorkor Korsah/ [Ashesi University](#)

The Competition...



The African Robotics Network
(AFRON) \$10 Robot Design
Challenge:

Try to build an educational robot
for use in African schools for \$10!

APPROACHES TO ROBOT DESIGN/CONTROL

Robot Type

Help

Tethered

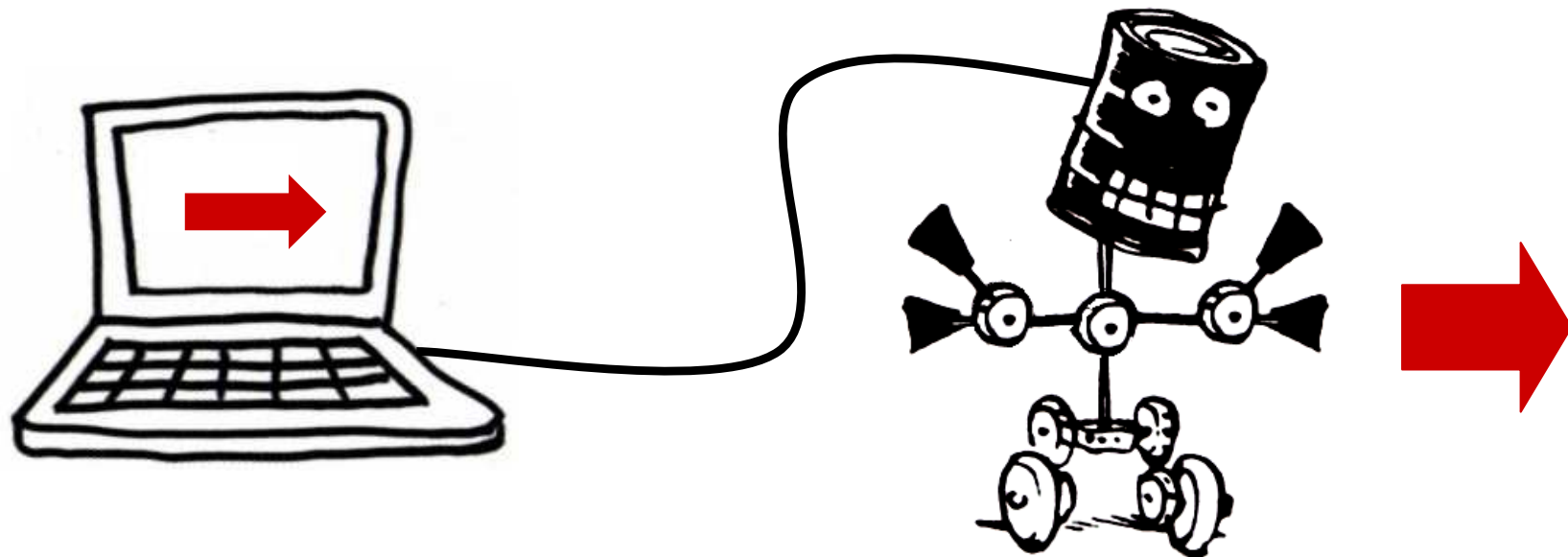


Traditional (roaming)

All-in-one (self-contained)

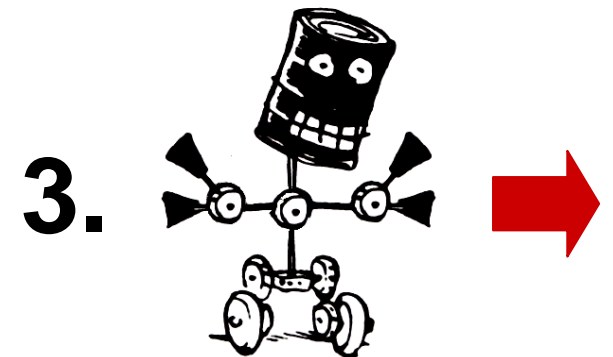
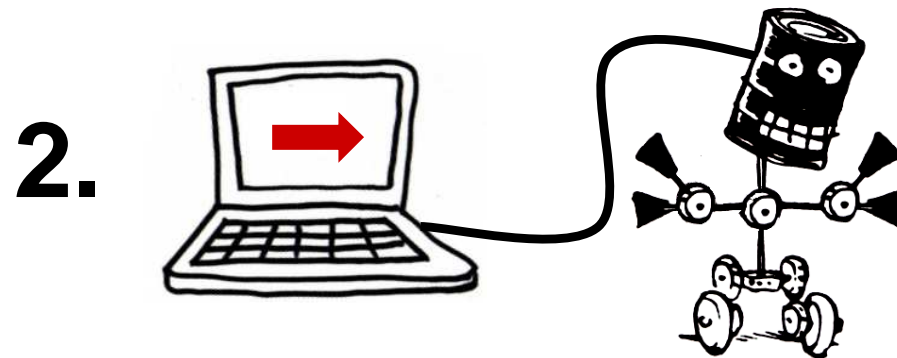
Tethered Robot

- Computing and programming off-board (e.g. laptop)



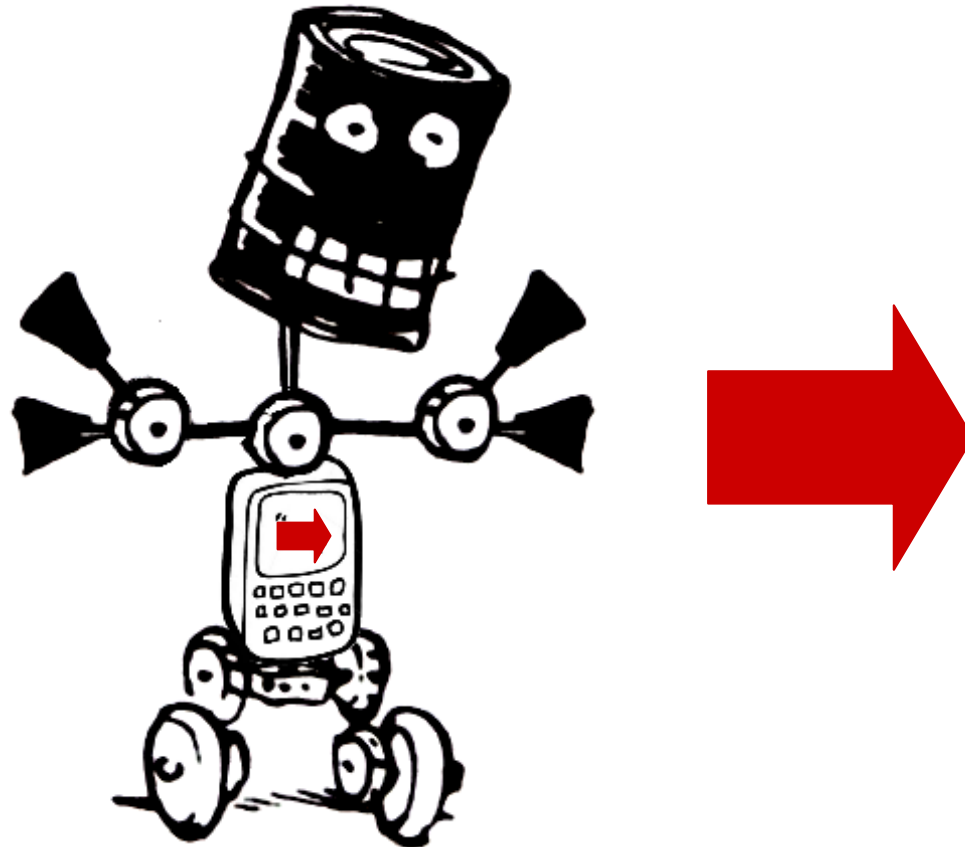
Traditional (Roaming) Robot

- Computing on-board, programming off-board (e.g microcontroller)



All-in-one (Self-contained) Robot

- Computing and programming on board



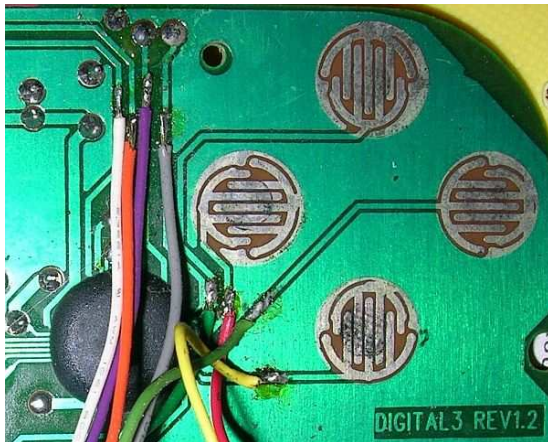
The Competition...



- June 14 to September 15, 2012
- Robot must be:
 - programmable (open source)
 - able to respond to its environment (-> at least one sensor)

Past Projects: 2005 - Present

Connect a wooden DDR mat to an Open Source simulator using a hacked joystick









My Idea...

- Make a tethered robot from a 100 Baht USB joystick.



- Use easy to find tools, parts & materials
- Simple design & construction so school students can make their own

Locomotion

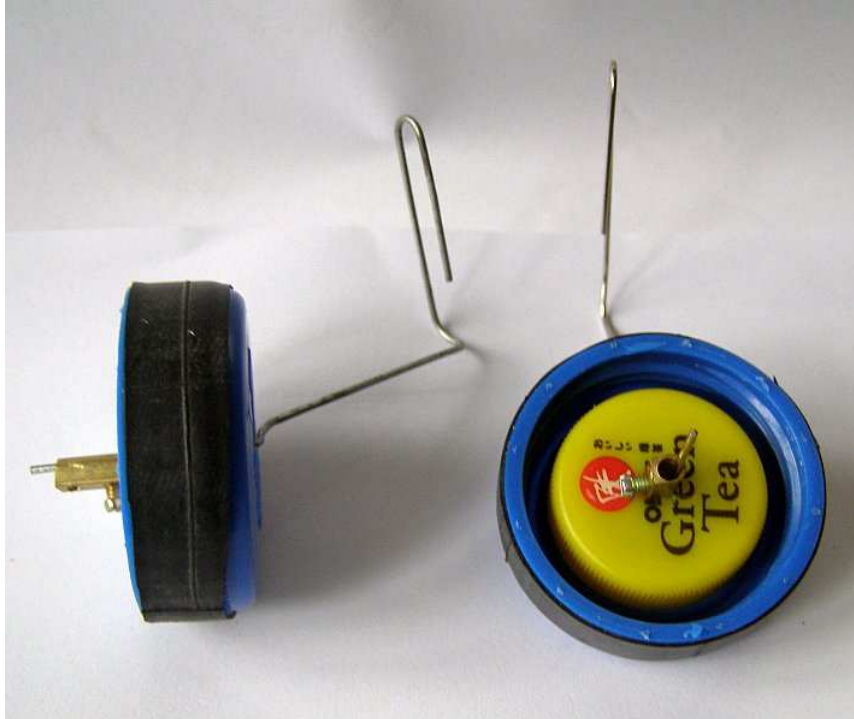
Use the joystick's rumble motors to drive wheels

1. Cut off the sides of a joystick
2. Remove the rumble weights
3. Turn the motors sideways



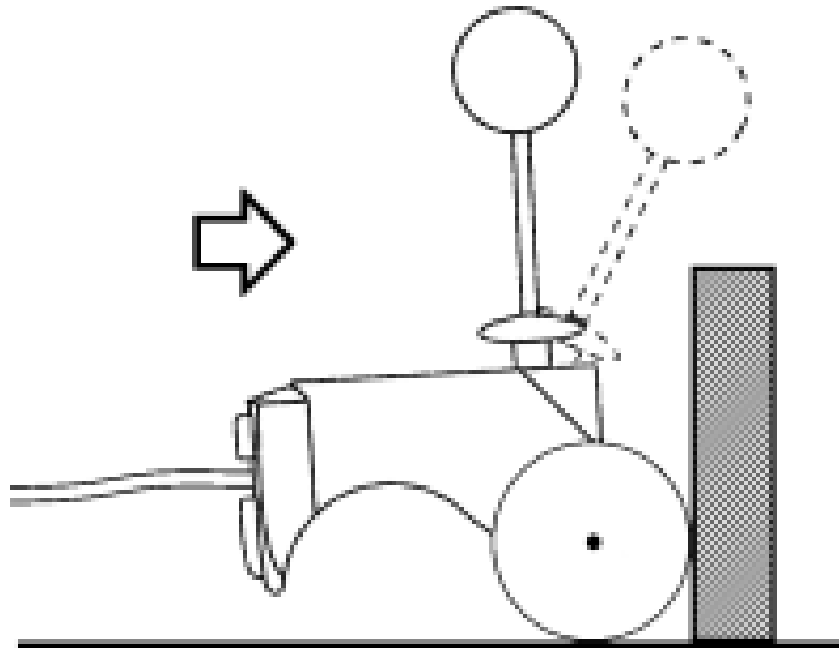
Wheels

- After a lot of experimentation I found a wheel design that worked!
- Paperclips provide suspension



Bump Sensor

- A Chupa Chupa lollipop mounted on a joystick acts as an inertia sensor
- When the robot is hit or if it hits something the joysticks move



The Name

“Chupa Chup” translates to something like “suck suck” in Spanish...



...so I called my robot “**Suckerbot**”

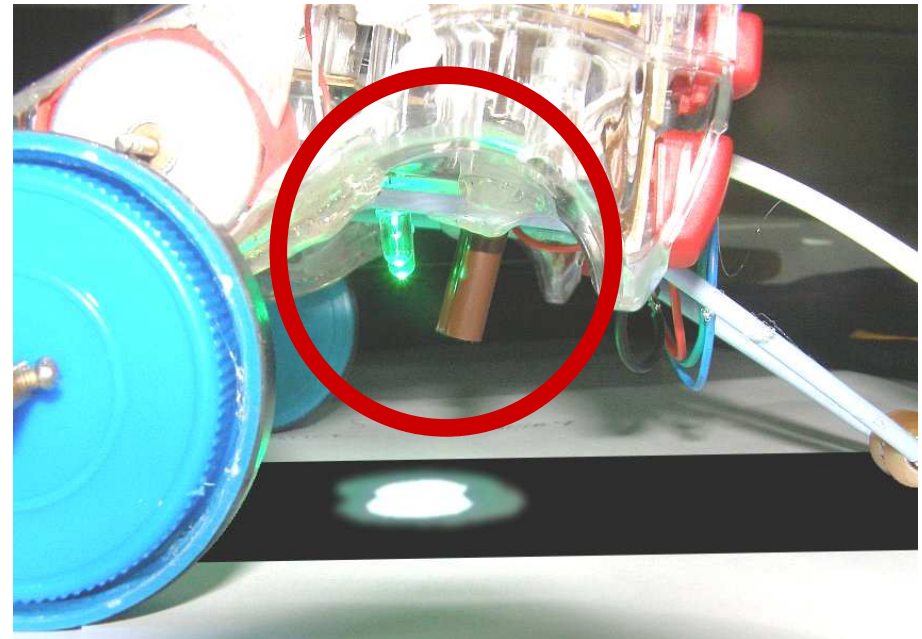
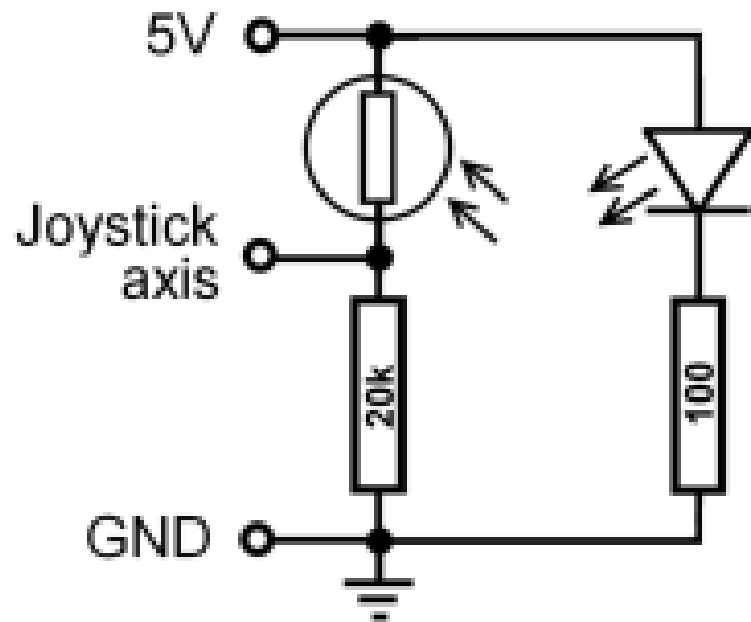
The Name

There were concerns about possible negative connotations of “sucker” in the US so I changed the name to:



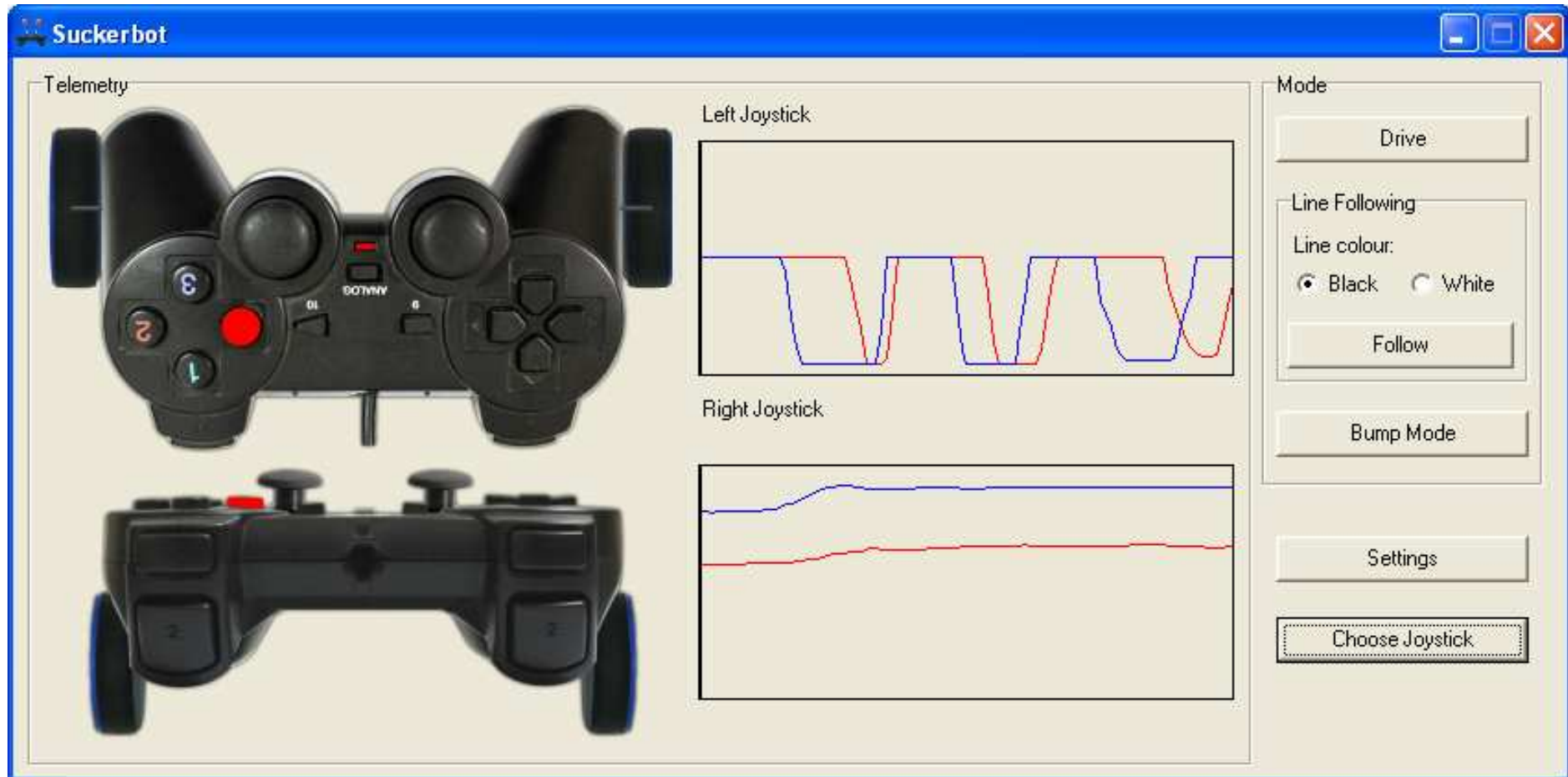
Line Detector

- I built a very simple circuit for detecting brightness using LEDs and Light Dependent Resistors (LDRs)
- The circuit is patched into one axis of the joysticks



Control Software

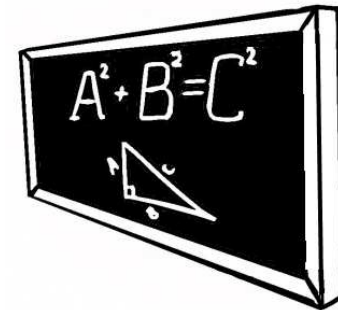
- Open source (GPL, on Google Code)
- Written using Delphi (Object Pascal)



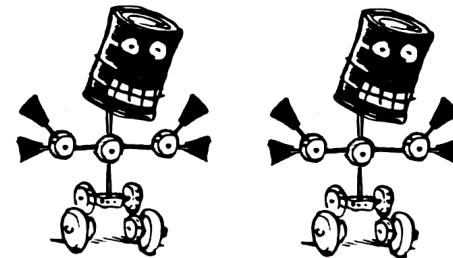
Judging

- 28 entries from all over the world
- 6 expert judges
- Criteria:

–Educational impact



–Reproducibility



–Affordability

\$???

And the Winner is...

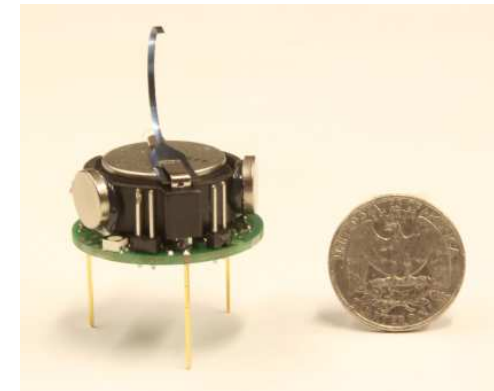
- Tethered

- Suckerbot (\$8.96)
Payap University



- Traditional (Roaming)

- Kilobot (\$43)
Harvard University, USA

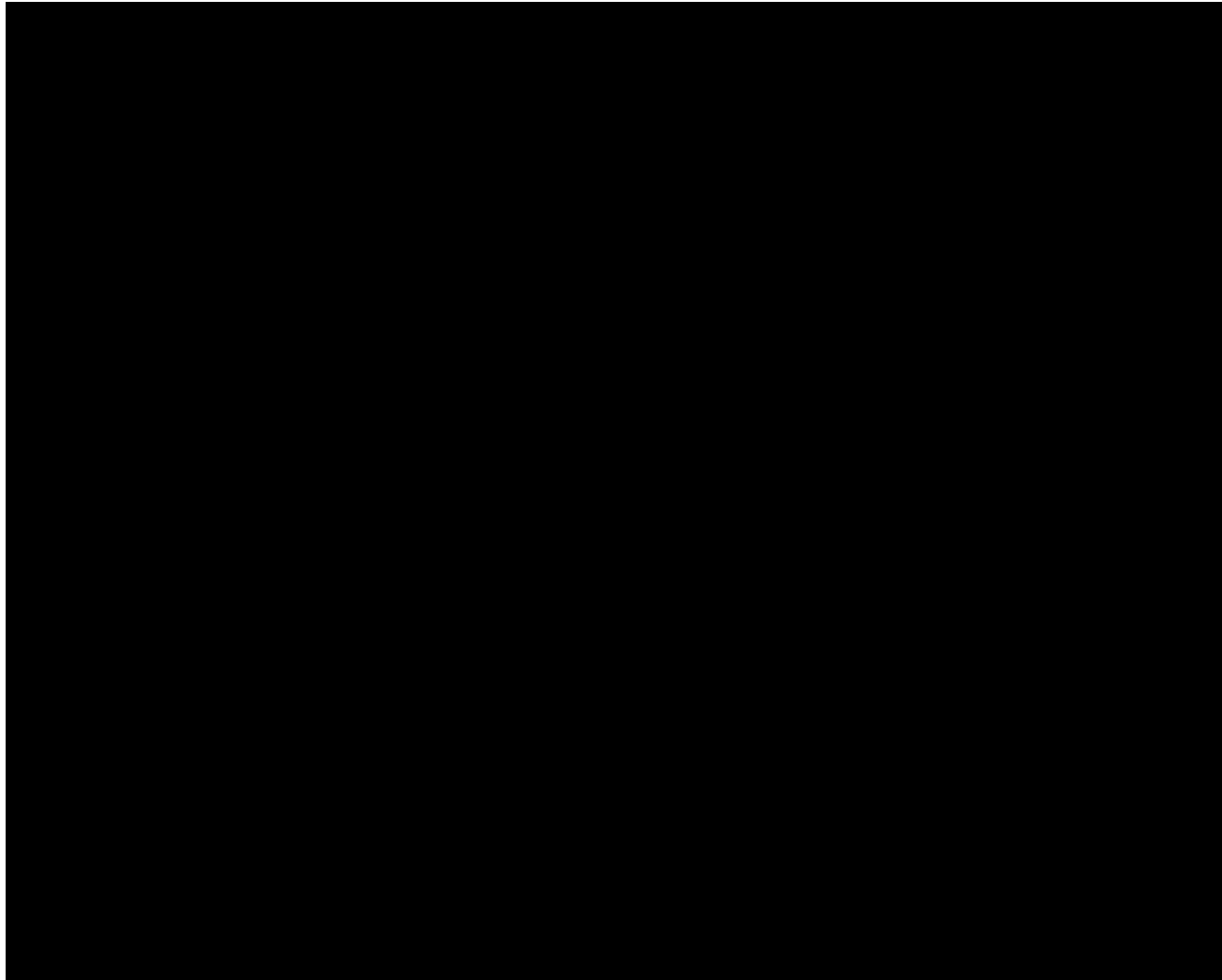


- All-in-one

- MITBOTS (\$33)
India



Video



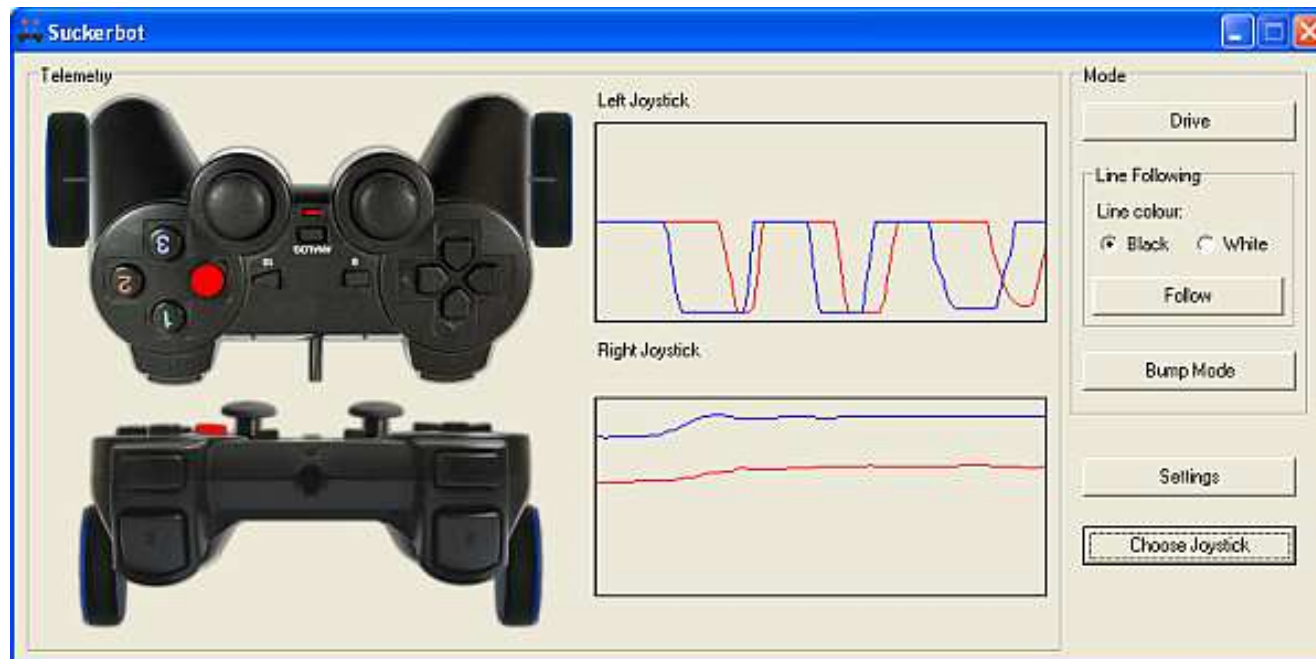
<http://youtu.be/Tt3yOkGEcKI>

In the Media



Software Limitations

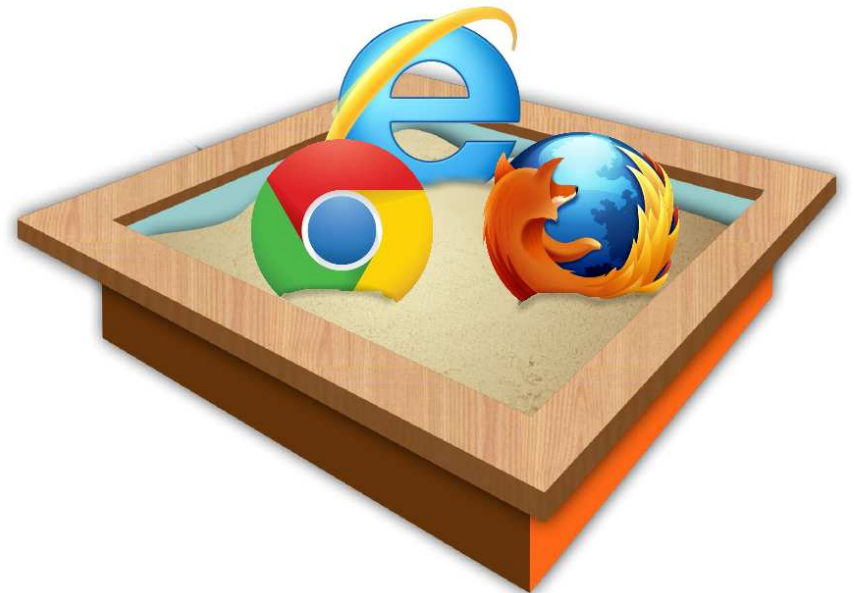
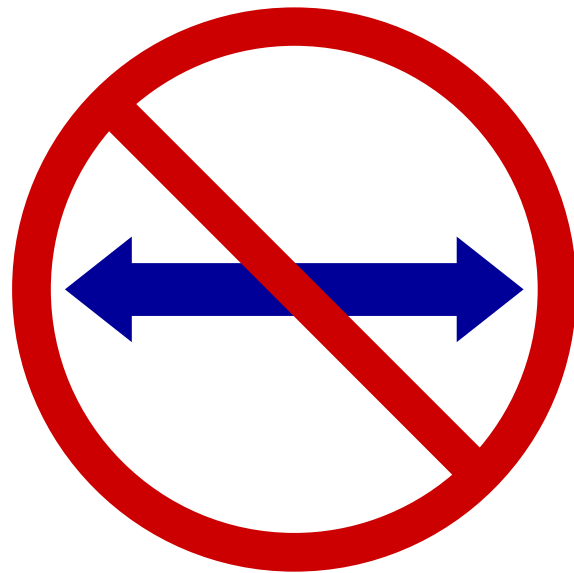
- The original control & telemetry code:
 - Only runs on Windows (USB HID library)
 - Requires a commercial IDE (now Delphi XE4 from Embarcadero)



Software Limitations

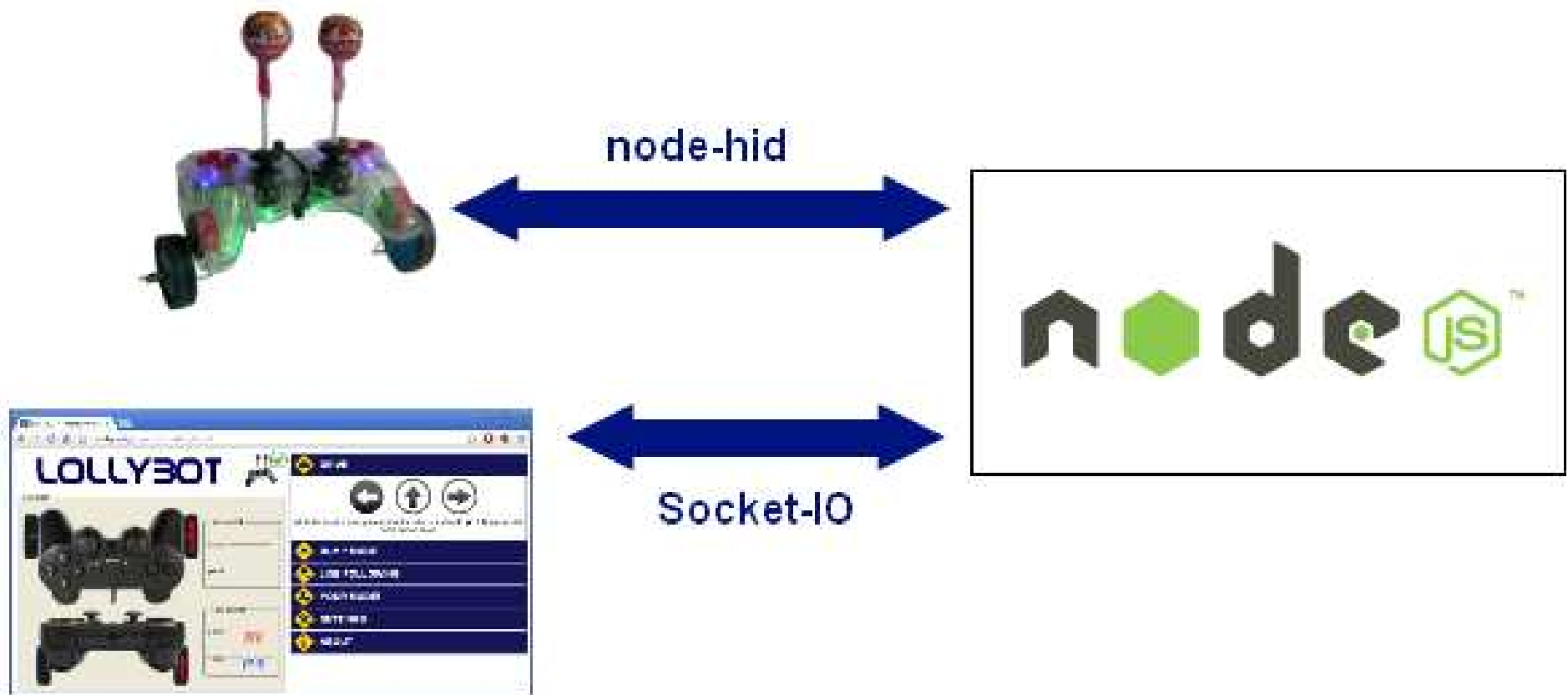
My son suggested building an HTML5 + JavaScript interface, but...

web browsers are sandboxed and can't access USB devices



Telemetry & Control

Solution: simple client-server architecture using Node.js - a stand alone JavaScript engine with access to the operating system



Telemetry & Control

Implemented in HTML5 & JavaScript using:

- Node.js
- Commander.js (plug-in for Node.js)
- jQuery
- jQuery Sparklines
- node-hid
- Socket.IO



Telemetry & Control

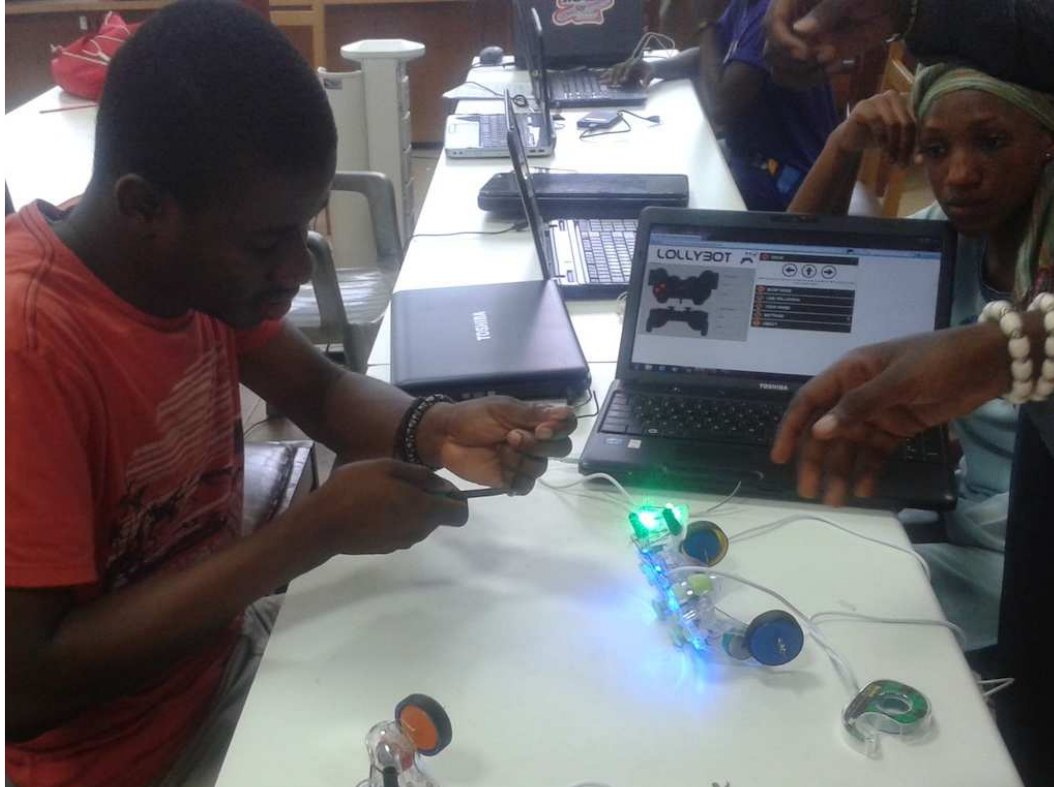
- Now free and cross-platform
- Client page can run in any HTML5 compliant browser – including mobile devices



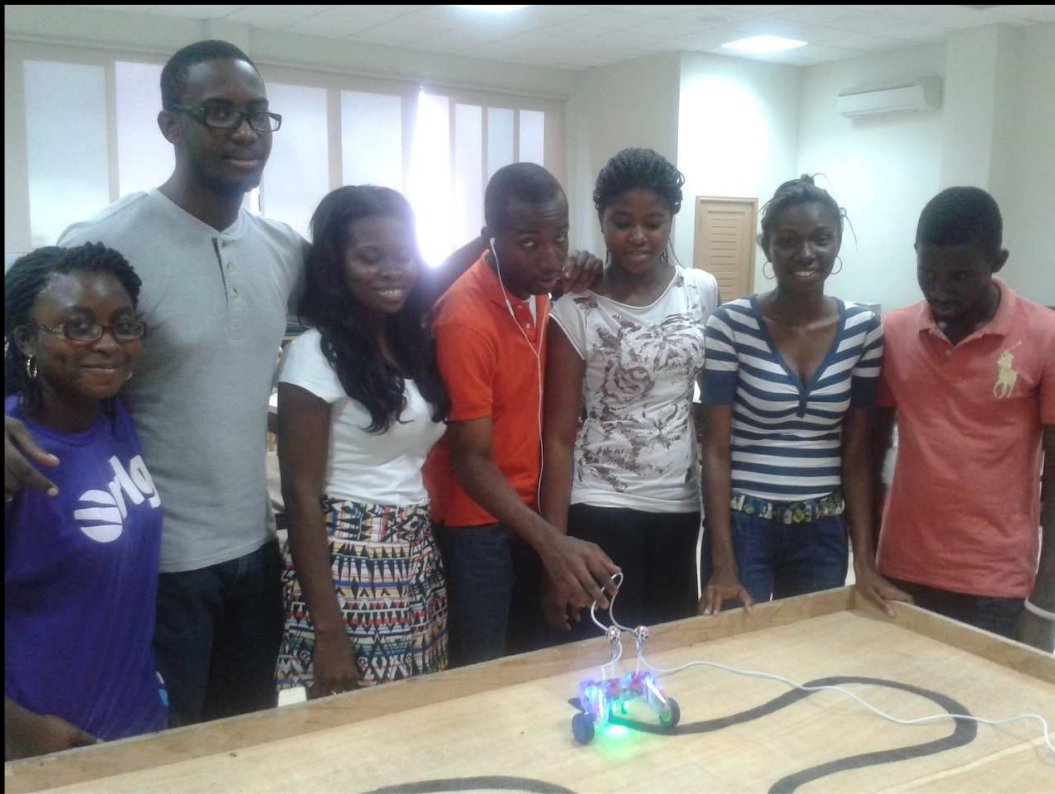


CMU, March 2013





Ghana, May 2013



Funding

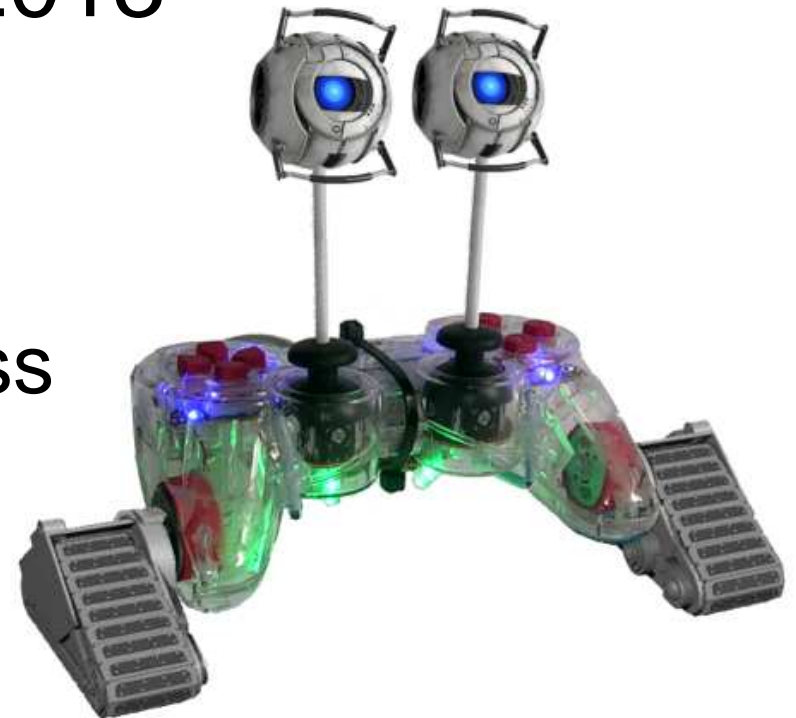
- “Ultra Affordable Robot Project”
- Reducing the cost of educational robotics by an order of magnitude
- IEEE Robotics & Automation Society are funding the first 100 - 200 Lollybots to be assembled in Ghana & distributed to African schools



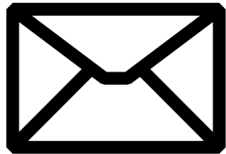
*IEEE
Robotics &
Automation
Society*

2013 Design Challenge

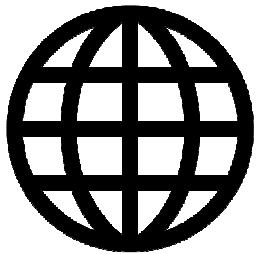
- Encouraging people to build, improve upon, and create teaching materials for the winning designs
- June 18 – September 18, 2013
- Four categories:
 - Improve Software
 - Improve H/W or build process
 - Create teaching curriculum
 - Run a workshop



Questions?



thomas_t@payap.ac.th



<http://tomtilley.net/projects/suckerbot>
<http://code.google.com/p/lollybot>